

Chapter 6. Converter Circuits

5 Questions

6.1. Circuit manipulations

6.2. A short list of
converters

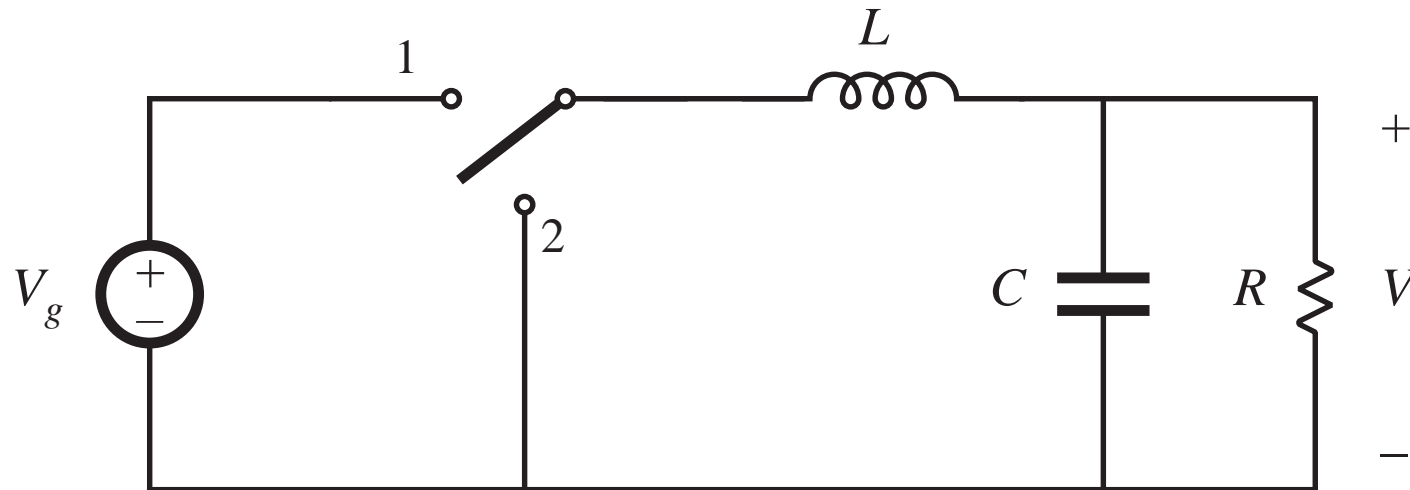
6.3. Transformer isolation

6.4. Converter evaluation
and design

6.5. Summary of key
points

- Where do the boost, buck-boost, and other converters originate?
- How can we obtain a converter having given desired properties?
- What converters are possible?
- How can we obtain transformer isolation in a converter?
- For a given application, which converter is best?

6.1. Circuit Manipulations



Begin with buck converter: derived in Chapter 1 from first principles

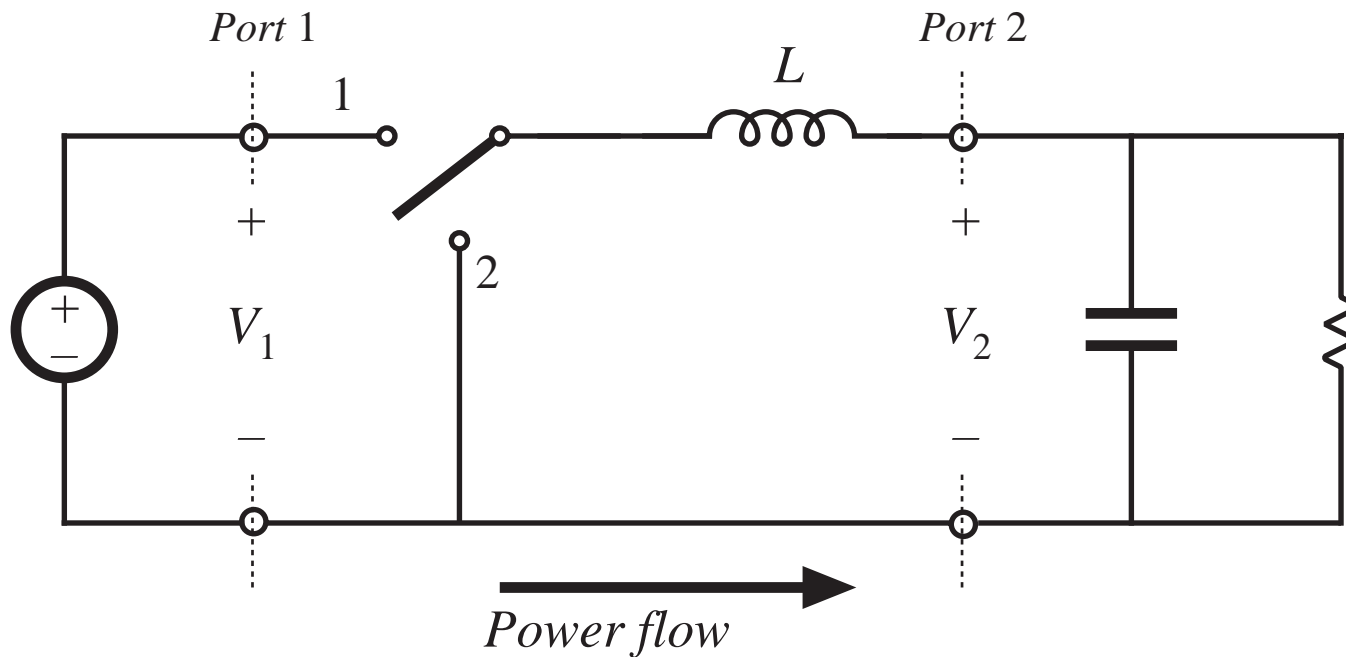
- Switch changes dc component, low-pass filter removes switching harmonics
- Conversion ratio is $M = D$

6.1.1. Inversion of source and load

Interchange power input and output ports of a converter

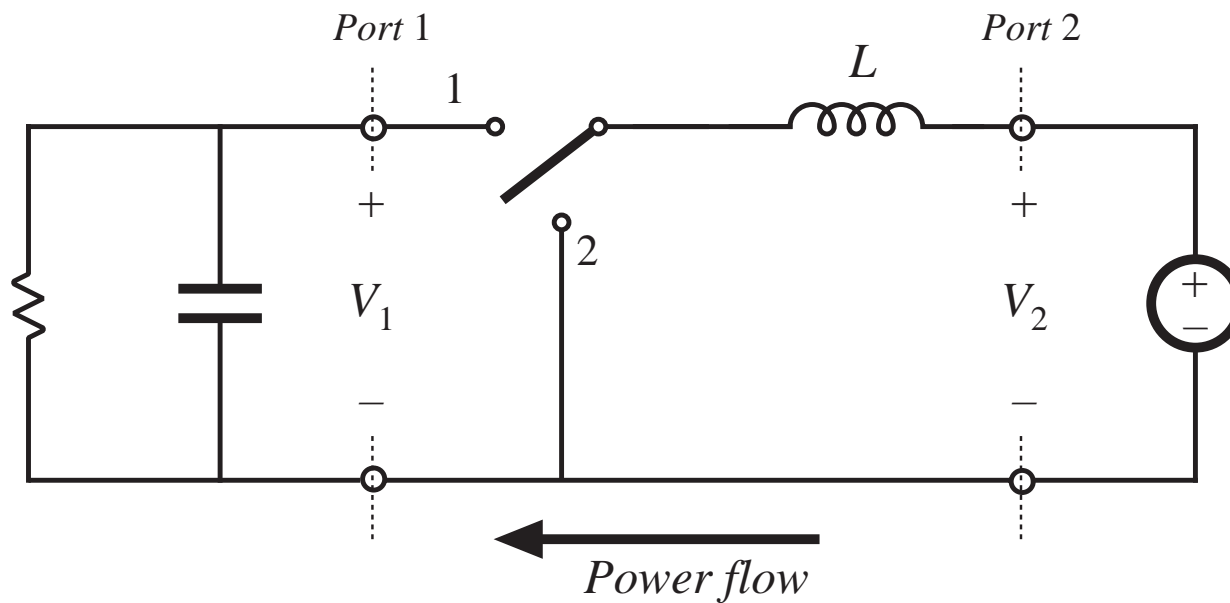
Buck converter example

$$V_2 = DV_1$$



Inversion of source and load

Interchange power source and load:

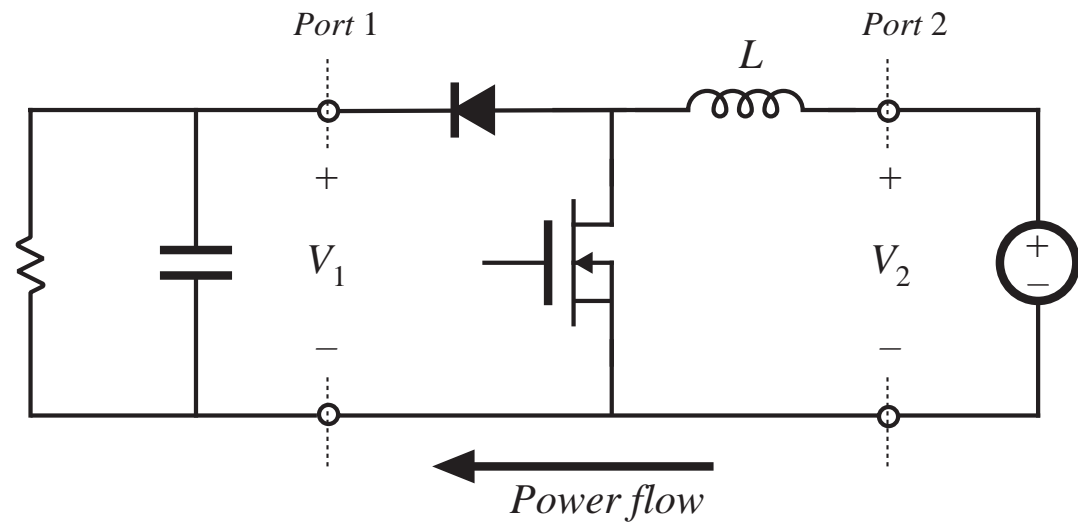


$$V_2 = DV_1$$

$$V_1 = \frac{1}{D} V_2$$

Realization of switches as in Chapter 4

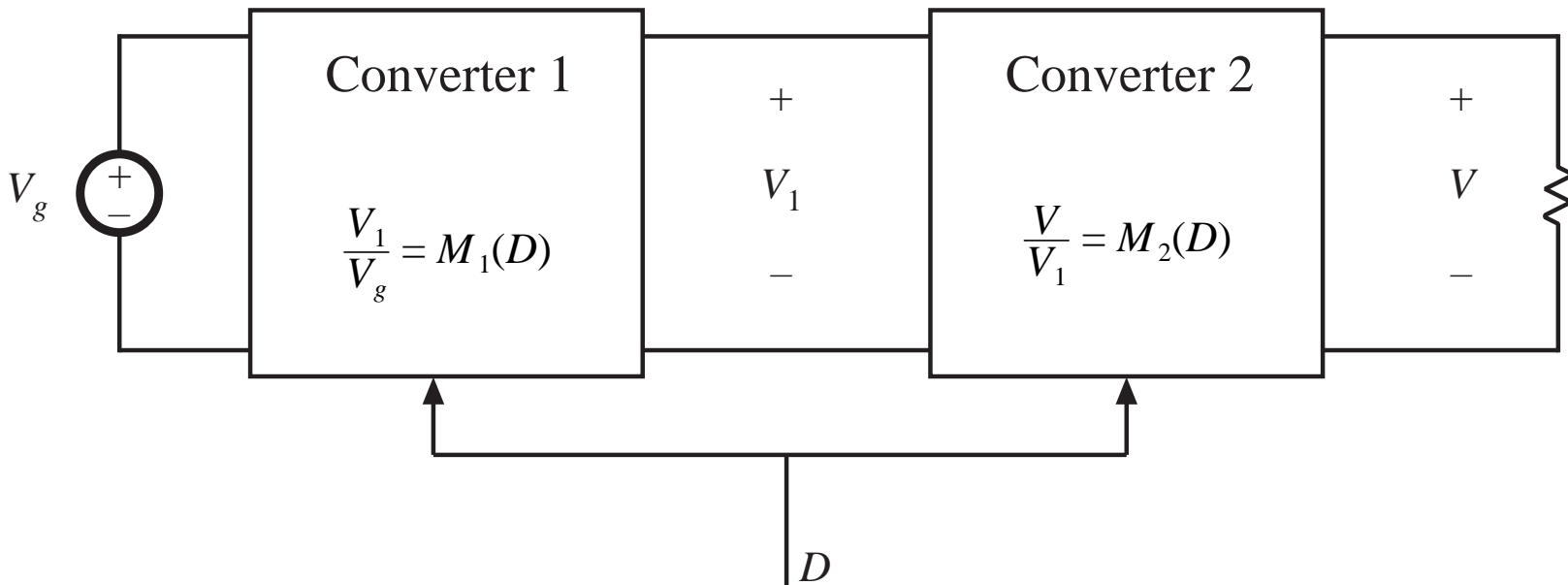
- Reversal of power flow requires new realization of switches
- Transistor conducts when switch is in position 2
- Interchange of D and D'



$$V_1 = \frac{1}{D'} V_2$$

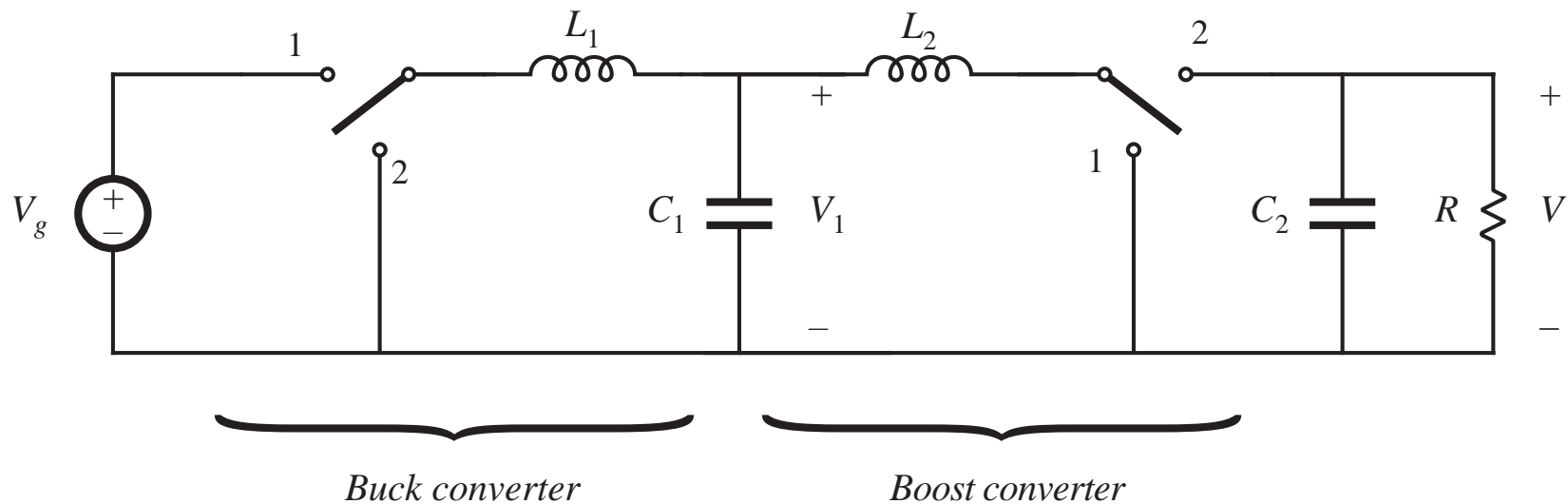
Inversion of buck converter yields boost converter

6.1.2. Cascade connection of converters



$$\begin{aligned} V_1 &= M_1(D) V_g \\ V &= M_2(D) V_1 \end{aligned} \quad \longrightarrow \quad \frac{V}{V_g} = M(D) = M_1(D) M_2(D)$$

Example: buck cascaded by boost



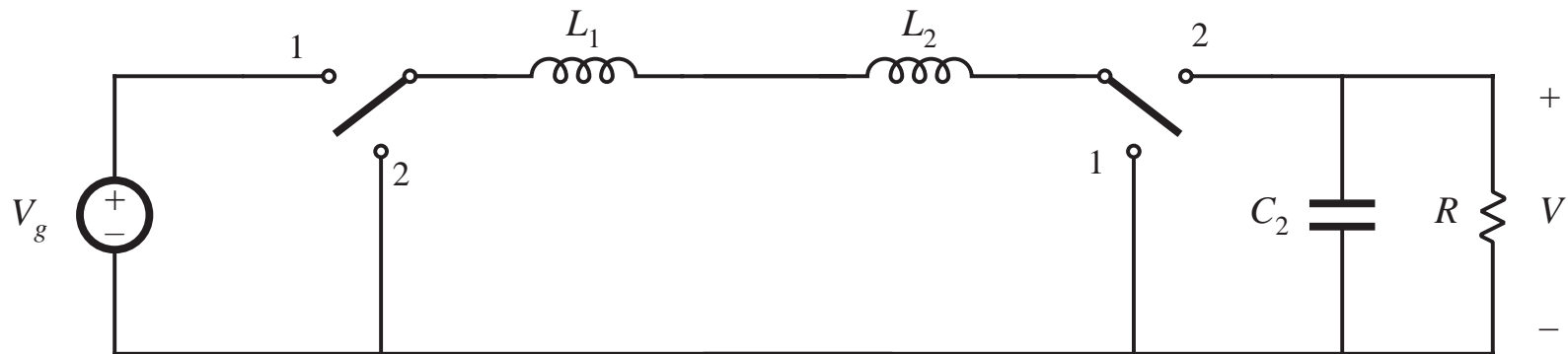
$$\frac{V_1}{V_g} = D$$
$$\frac{V}{V_1} = \frac{1}{1-D}$$



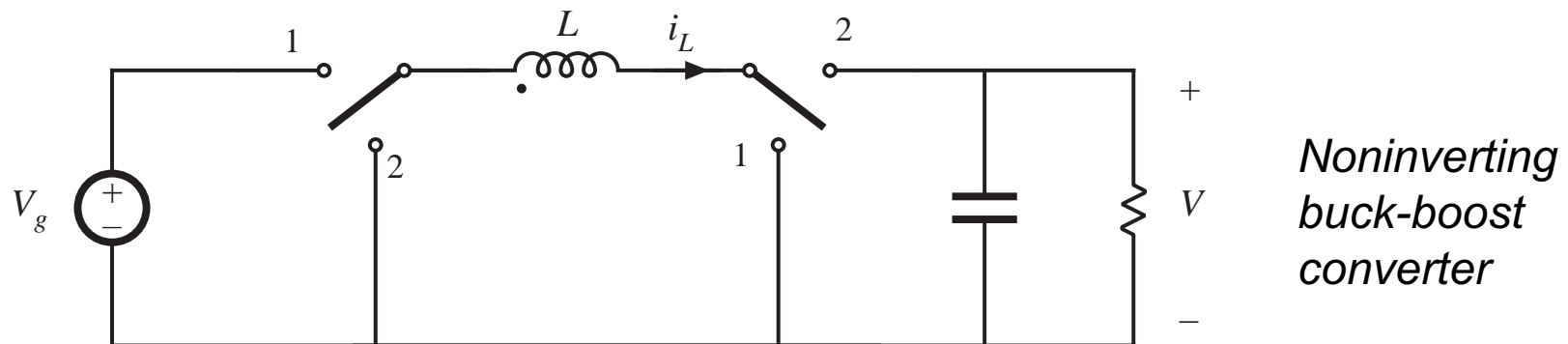
$$\frac{V}{V_g} = \frac{D}{1-D}$$

Buck cascaded by boost: simplification of internal filter

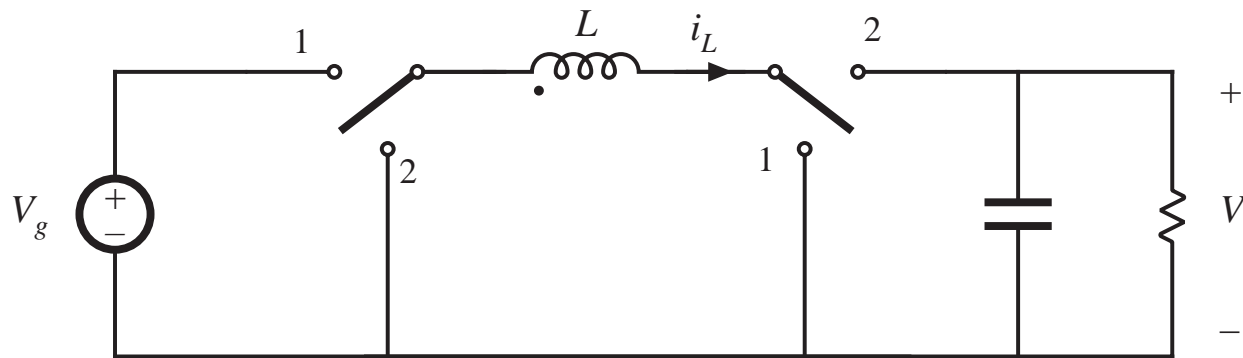
Remove capacitor C_1



Combine inductors L_1 and L_2

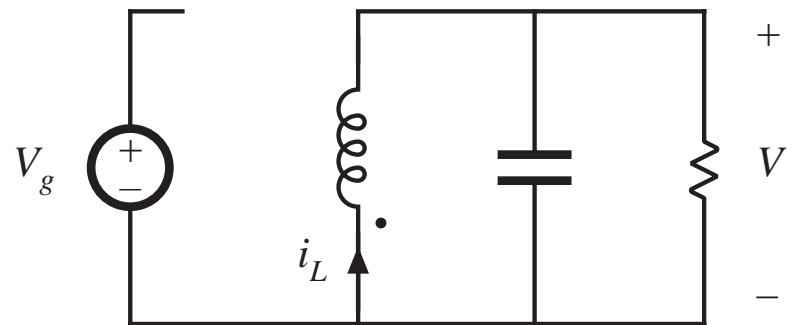
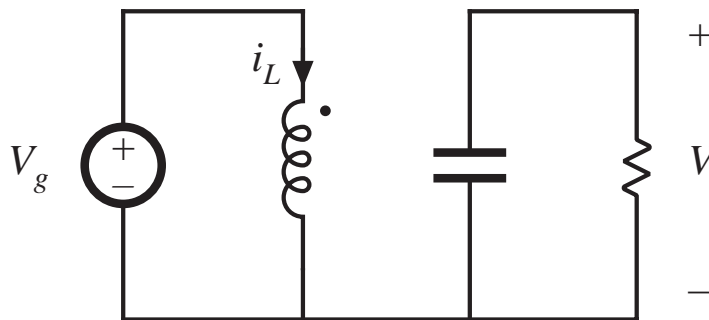


Noninverting buck-boost converter

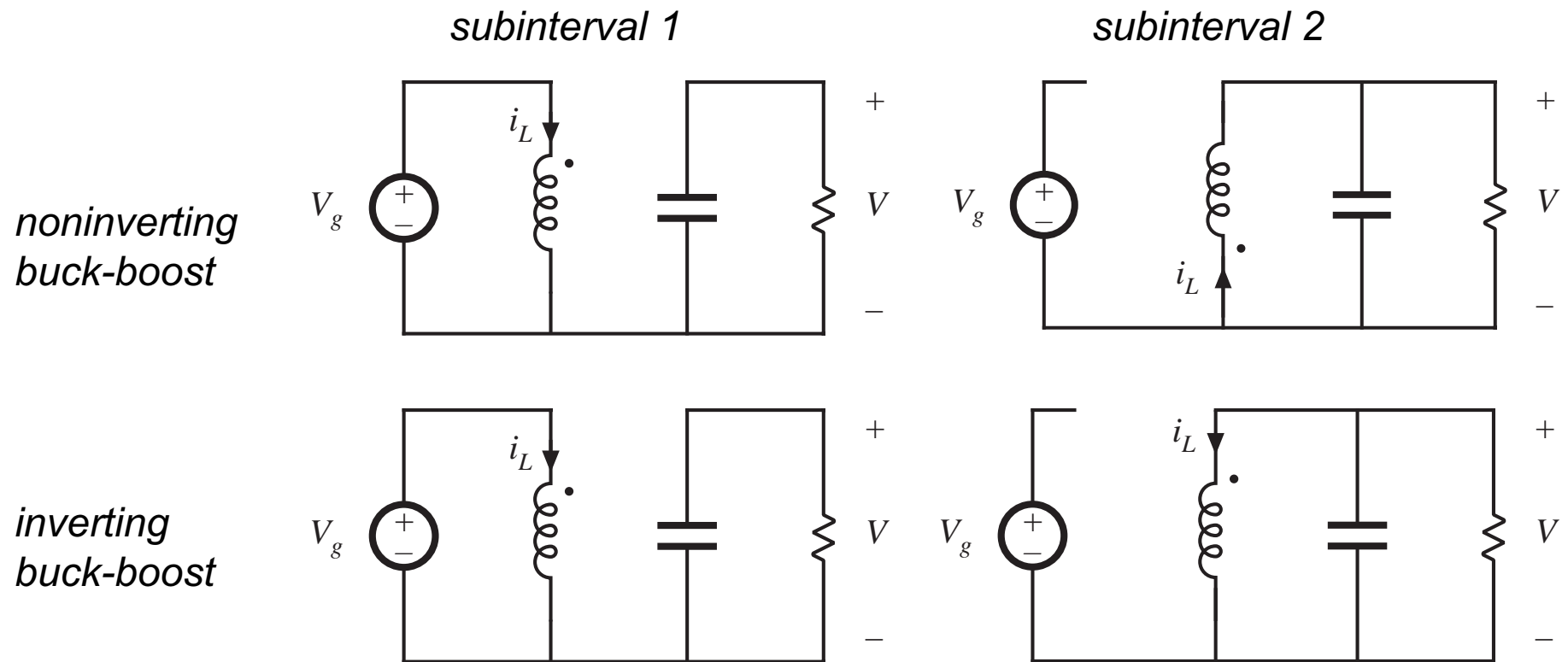


subinterval 1

subinterval 2

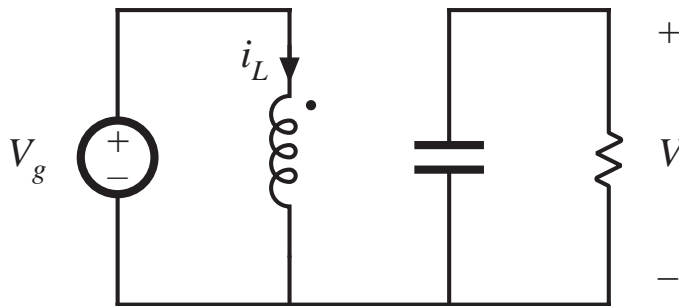


Reversal of output voltage polarity

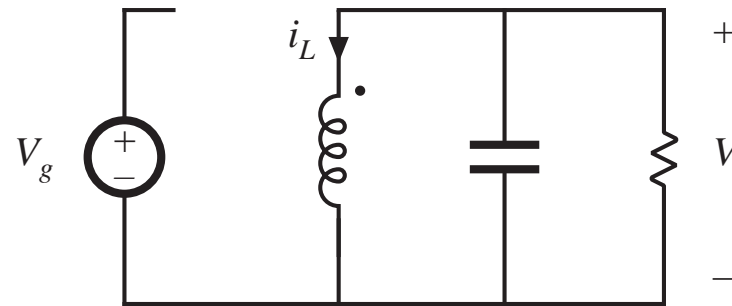


Reduction of number of switches: inverting buck-boost

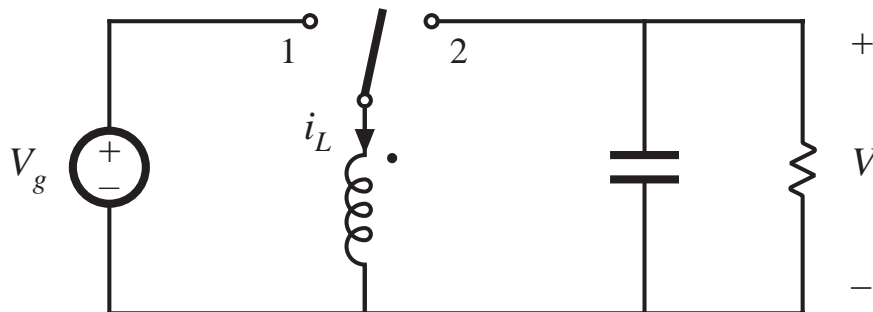
Subinterval 1



Subinterval 2



One side of inductor always connected to ground
— hence, only one SPDT switch needed:



$$\frac{V}{V_g} = -\frac{D}{1-D}$$

Discussion: cascade connections

- Properties of buck-boost converter follow from its derivation as buck cascaded by boost

Equivalent circuit model: buck $1:D$ transformer cascaded by boost $D':1$ transformer

Pulsating input current of buck converter

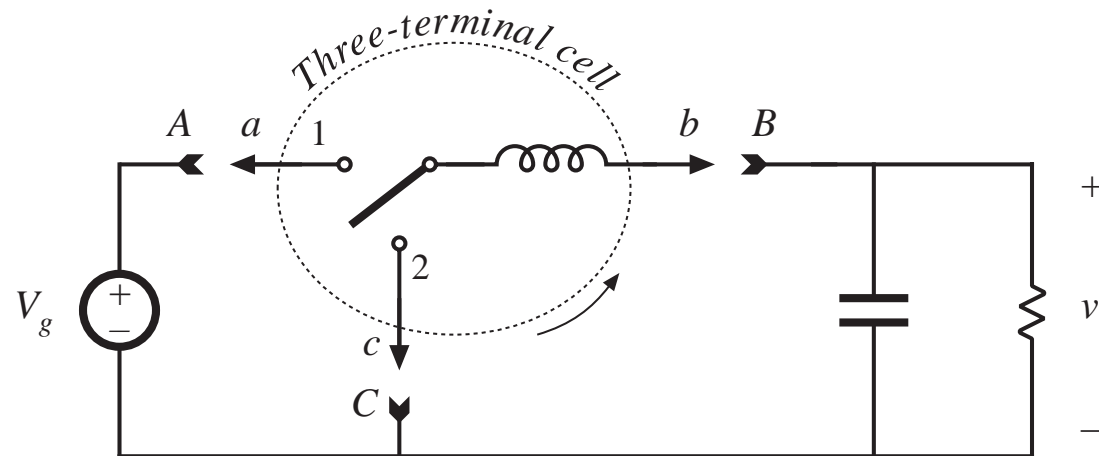
Pulsating output current of boost converter

- Other cascade connections are possible

Cuk converter: boost cascaded by buck

6.1.3. Rotation of three-terminal cell

Treat inductor and SPDT switch as three-terminal cell:

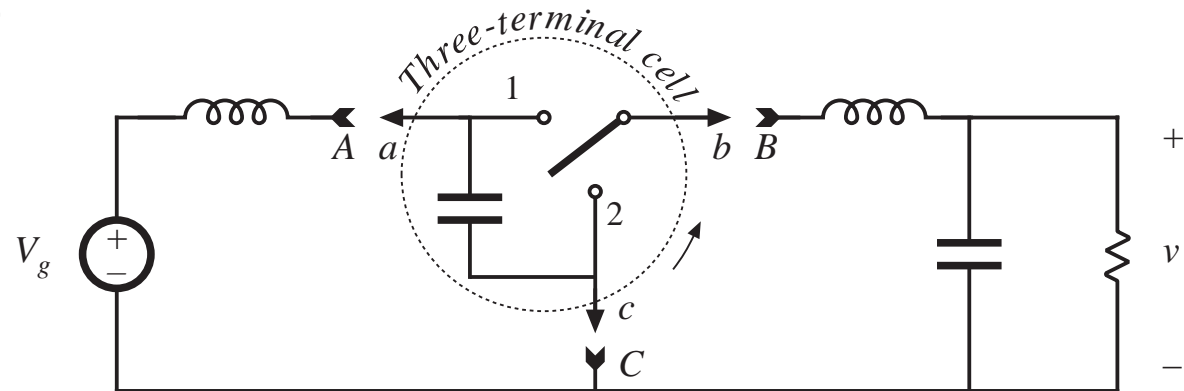


Three-terminal cell can be connected between source and load in three nontrivial distinct ways:

- | | |
|-------------|----------------------|
| a-A b-B c-C | buck converter |
| a-C b-A c-B | boost converter |
| a-A b-C c-B | buck-boost converter |

Rotation of a dual three-terminal network

A capacitor and SPDT switch as a three-terminal cell:



Three-terminal cell can be connected between source and load in three nontrivial distinct ways:

a-A b-B c-C

buck converter with L-C input filter

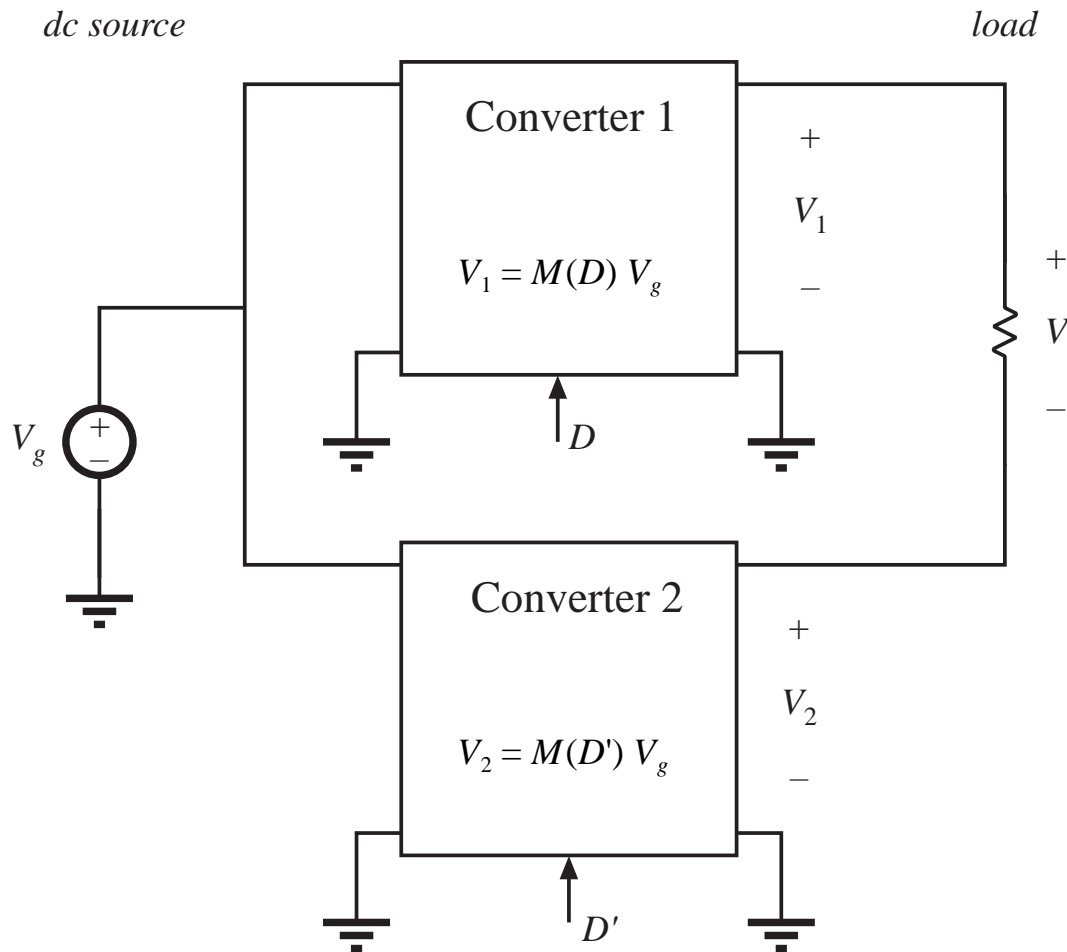
a-C b-A c-B

boost converter with L-C output filter

a-A b-C c-B

Cuk converter

6.1.4. Differential connection of load to obtain bipolar output voltage

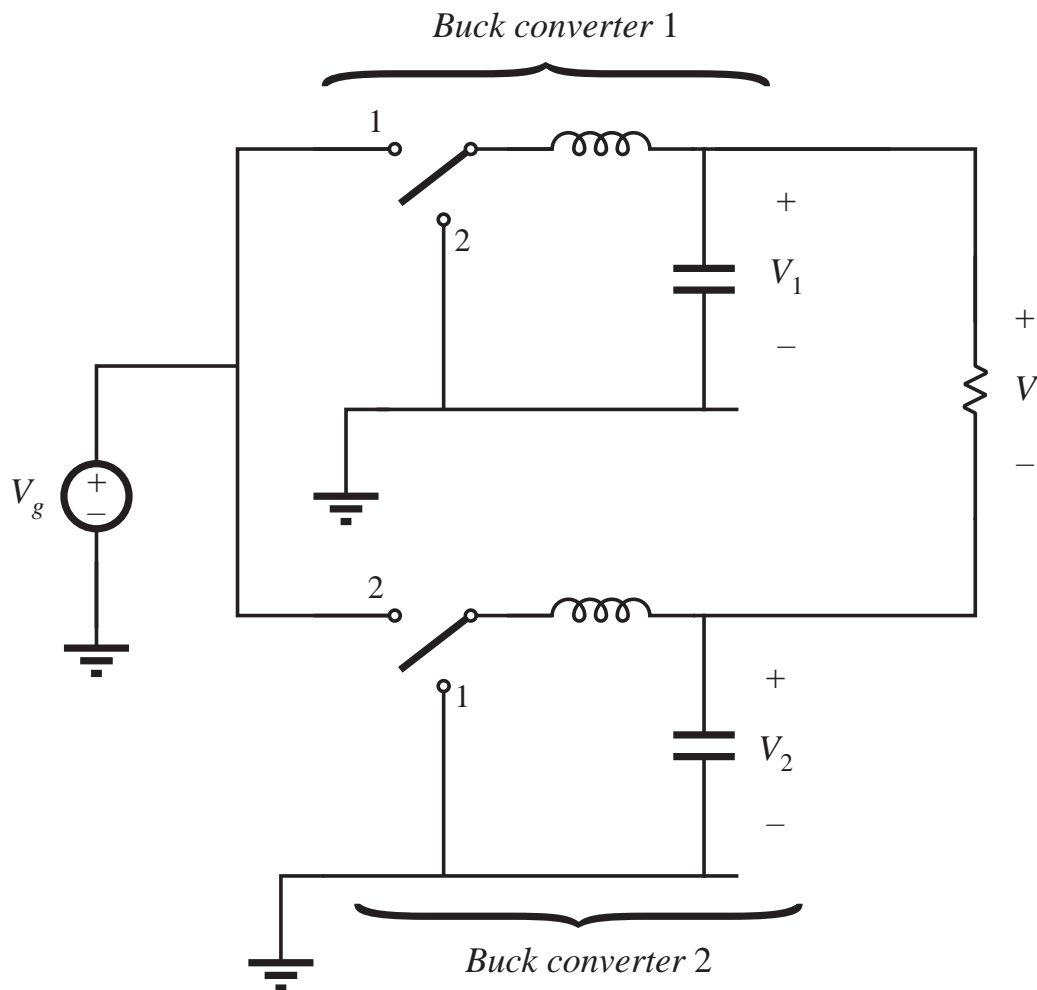


Differential load voltage is

$$V = V_1 - V_2$$

The outputs V_1 and V_2 may both be positive, but the differential output voltage V can be positive or negative.

Differential connection using two buck converters



Converter #1 transistor driven with **duty cycle D**

Converter #2 transistor driven with **duty cycle complement D'**

Differential load voltage is

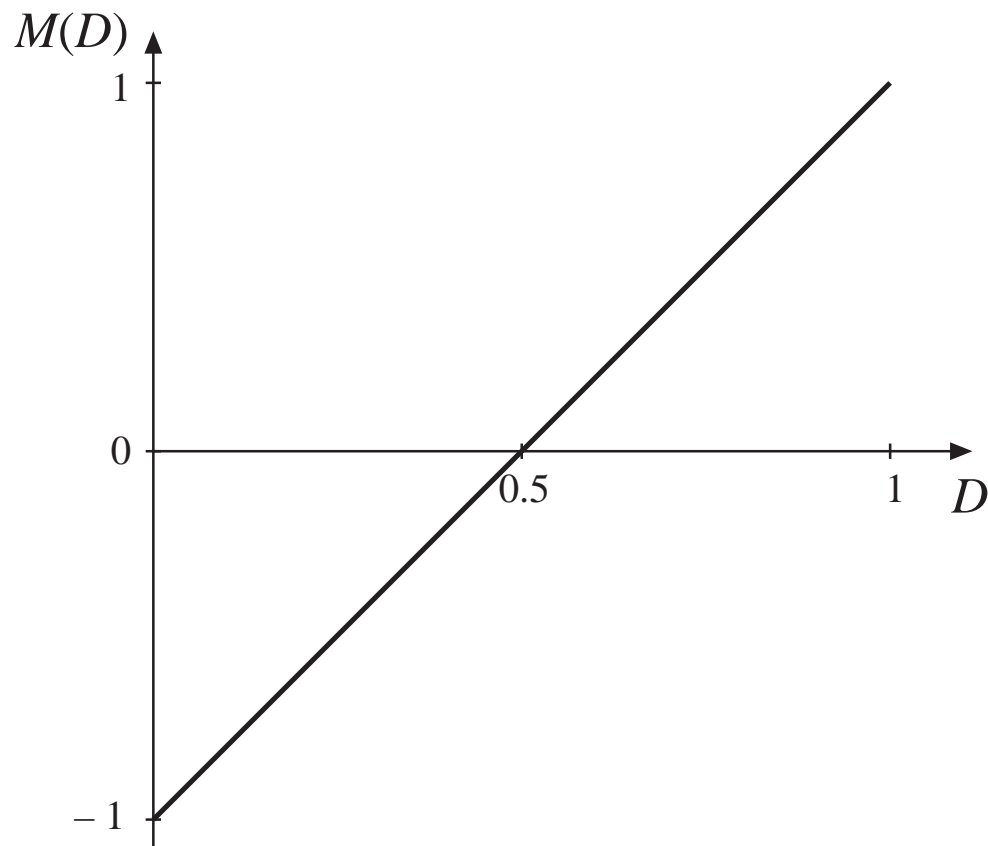
$$V = DV_g - D'V_g$$

Simplify:

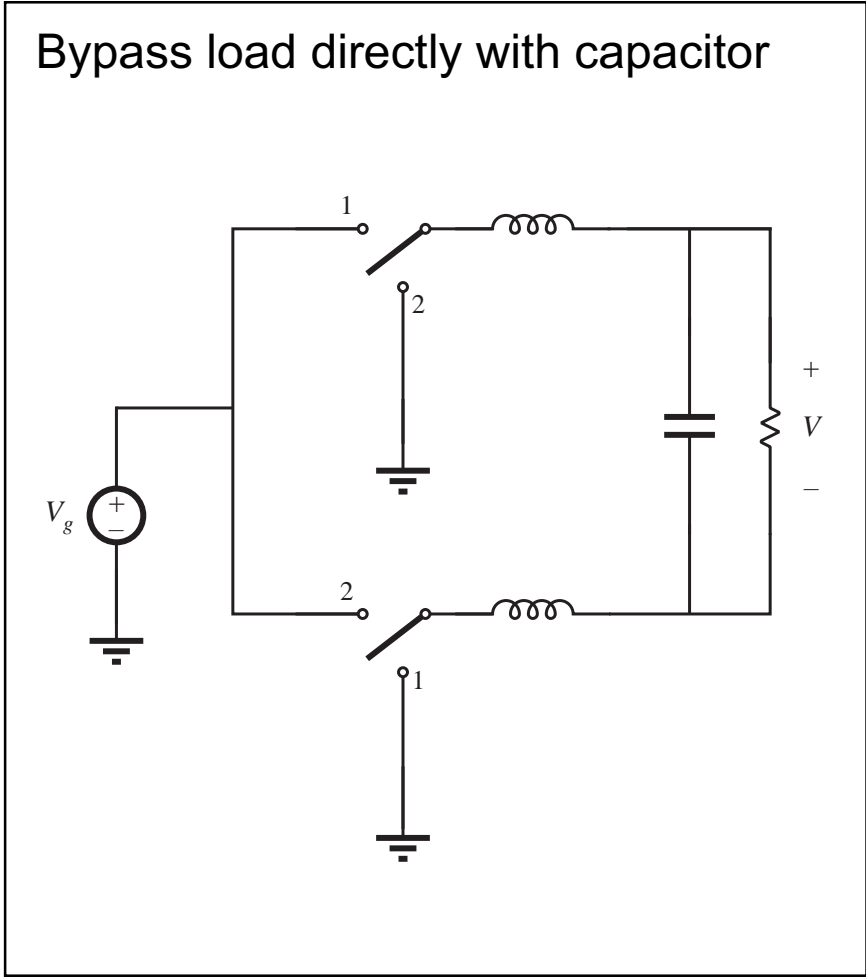
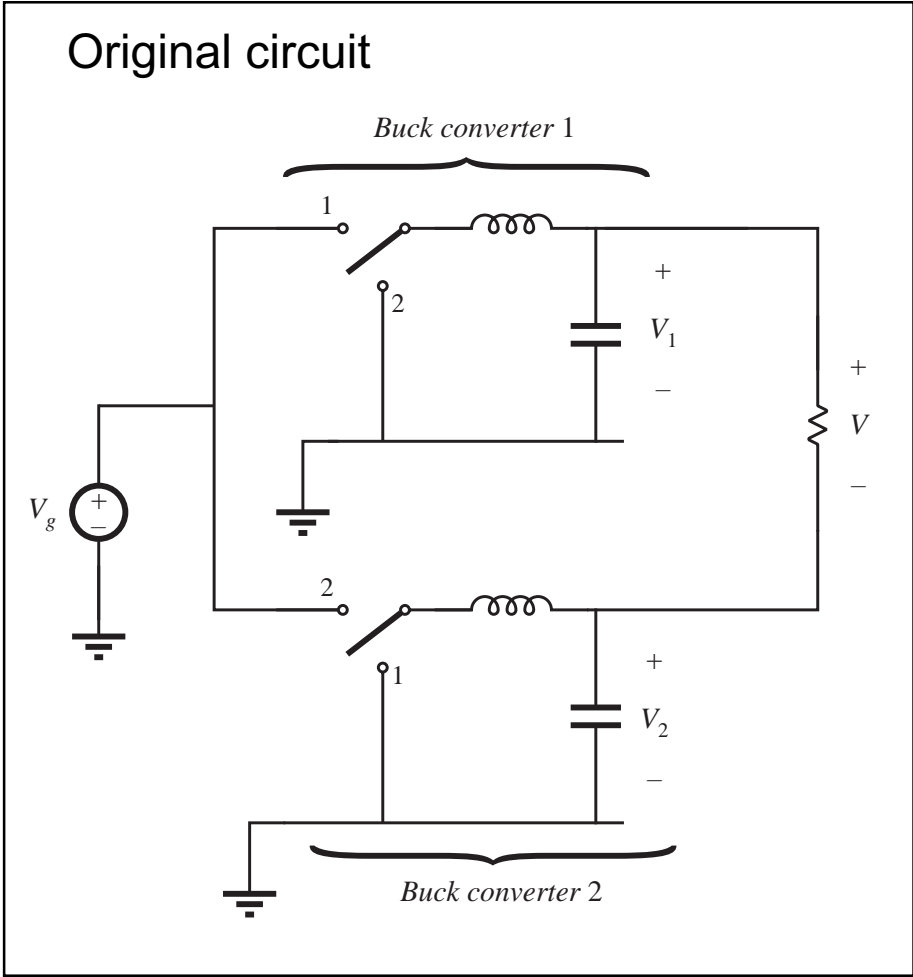
$$V = (2D - 1)V_g$$

Conversion ratio $M(D)$, differentially-connected buck converters

$$V = (2D - 1)V_g$$

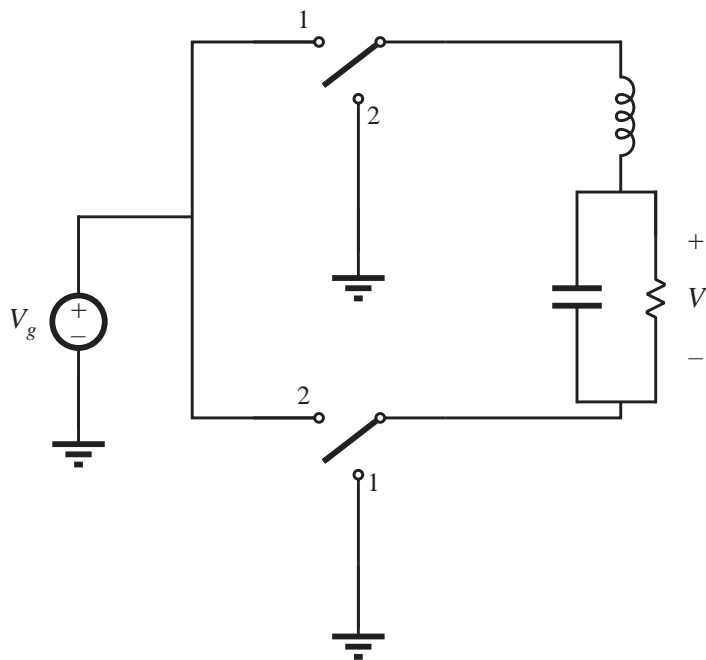


Simplification of filter circuit, differentially-connected buck converters

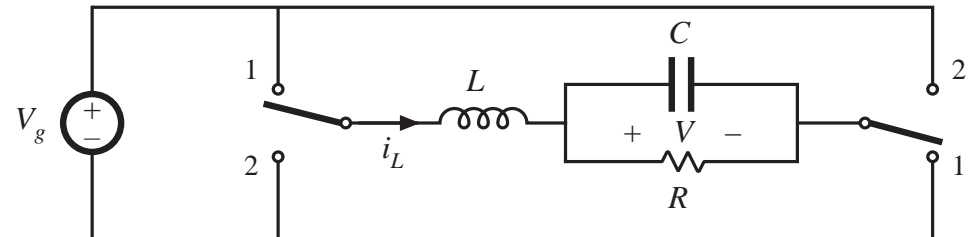


Simplification of filter circuit, differentially-connected buck converters

Combine series-connected
inductors



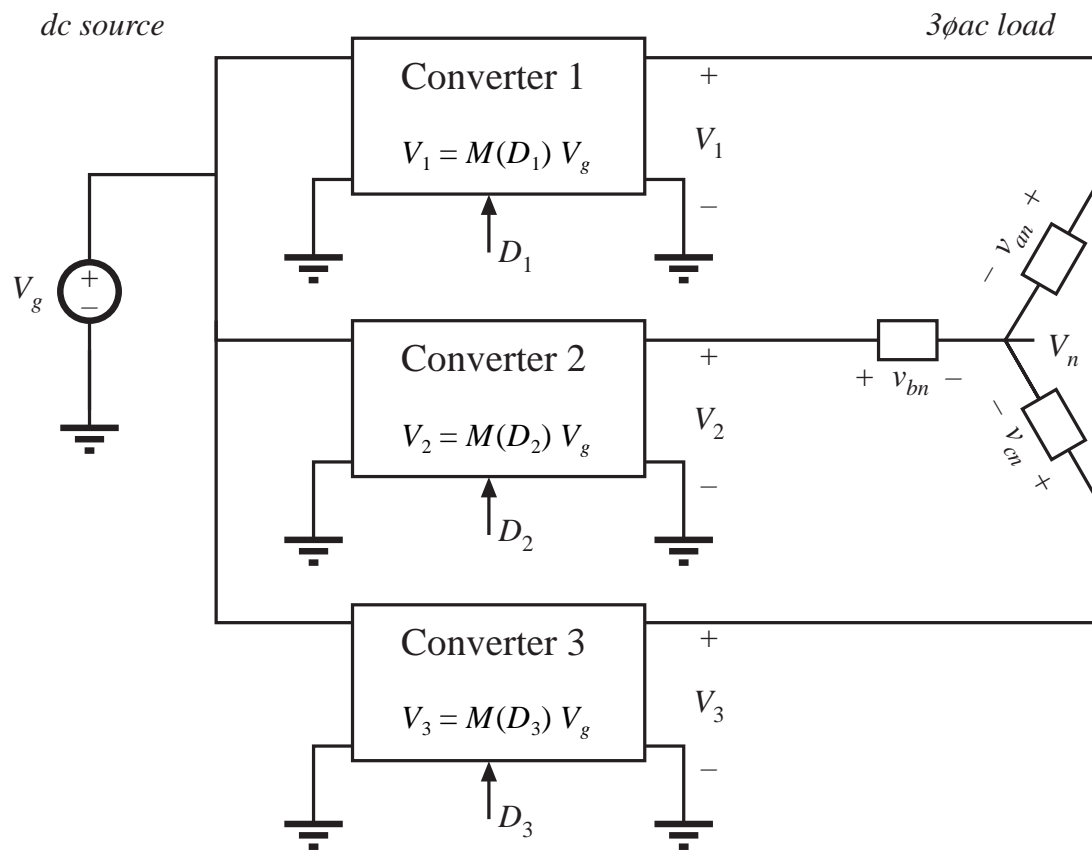
Re-draw for clarity



H-bridge, or bridge inverter

Commonly used in single-phase
inverter applications and in servo
amplifier applications

Differential connection to obtain 3 ϕ inverter



With balanced 3 ϕ load, neutral voltage is

$$V_n = \frac{1}{3} (V_1 + V_2 + V_3)$$

Phase voltages are

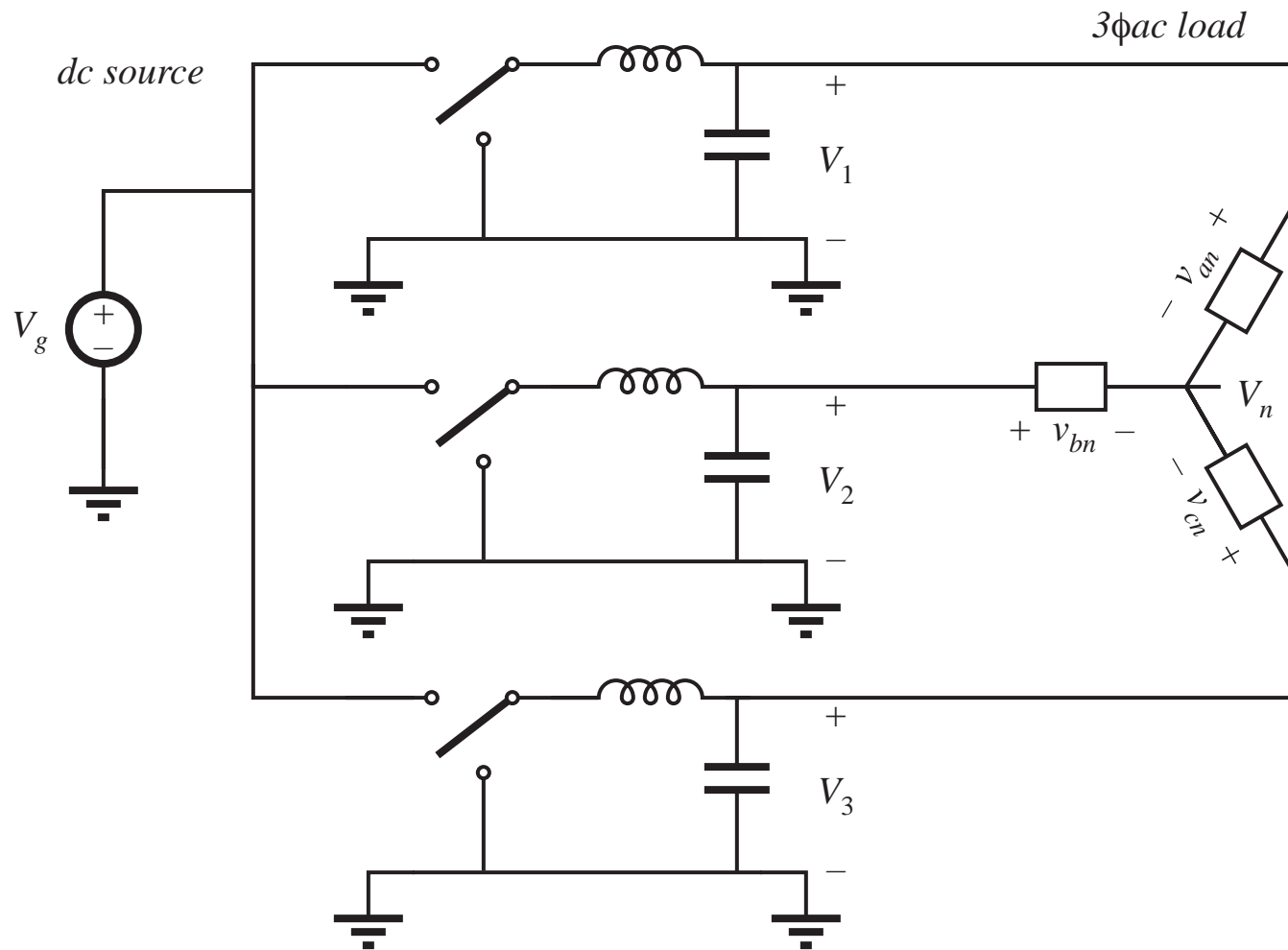
$$V_{an} = V_1 - V_n$$

$$V_{bn} = V_2 - V_n$$

$$V_{cn} = V_3 - V_n$$

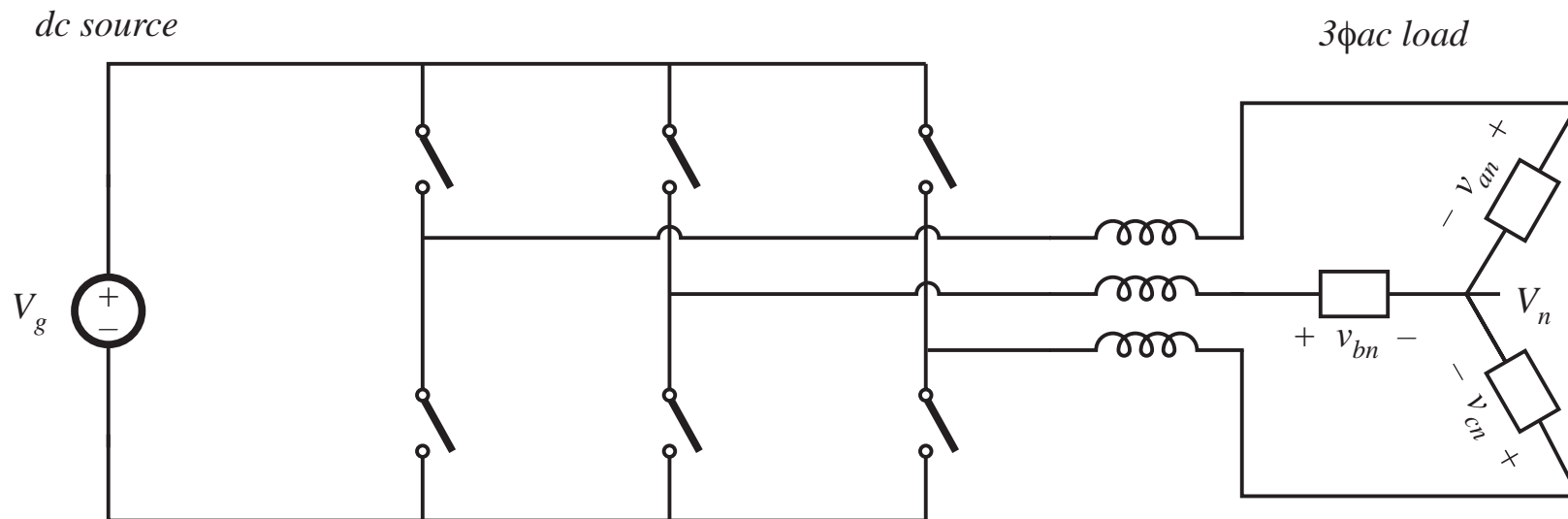
Control converters such that their output voltages contain the same dc biases. This dc bias will appear at the neutral point V_n . It then cancels out, so phase voltages contain no dc bias.

3 ϕ differential connection of three buck converters



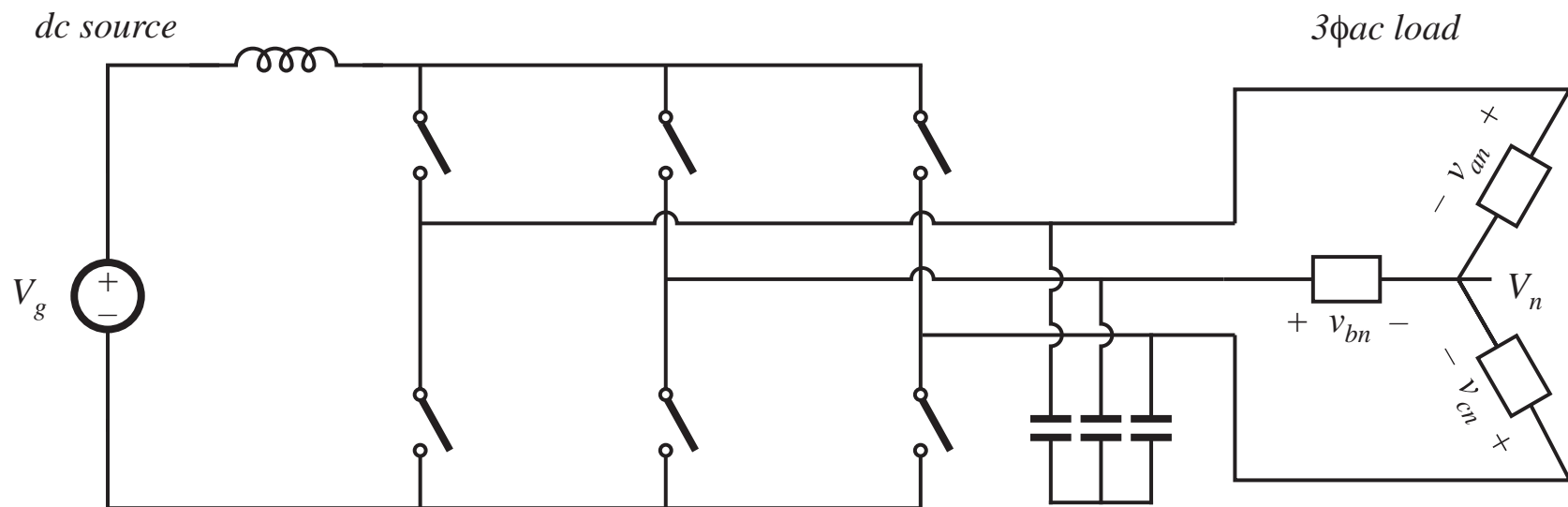
3 ϕ differential connection of three buck converters

Re-draw for clarity:



“Voltage-source inverter” or **buck-derived** three-phase inverter

The 3 ϕ current-source inverter



- Exhibits a **boost-type** conversion characteristic

6.2. A short list of converters

An **infinite** number of converters are possible, which contain switches embedded in a network of inductors and capacitors

Two simple classes of converters are listed here:

- **Single-input single-output converters containing a single inductor.** The switching period is divided into two subintervals. This class contains eight converters.
- **Single-input single-output converters containing two inductors.** The switching period is divided into two subintervals. Several of the more interesting members of this class are listed.

Single-input single-output converters containing one inductor

- Use switches to connect inductor between source and load, in one manner during first subinterval and in another during second subinterval
- There are a limited number of ways to do this, so all possible combinations can be found
- After elimination of degenerate and redundant cases, **eight** converters are found:

dc-dc converters

buck boost buck-boost noninverting buck-boost

dc-ac converters

bridge Watkins-Johnson

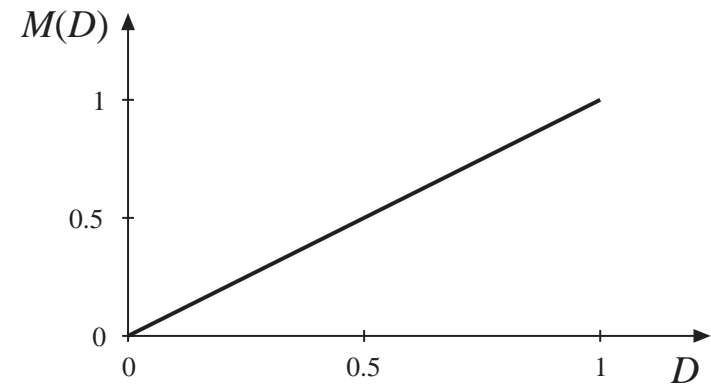
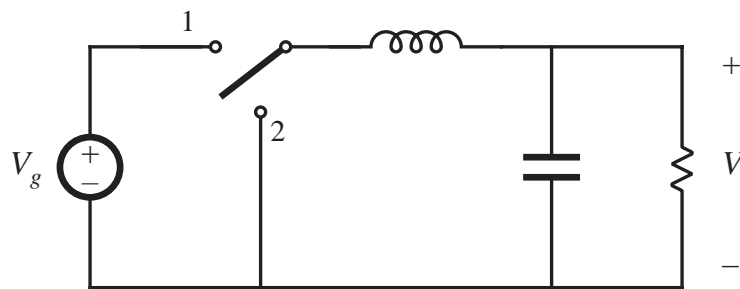
ac-dc converters

current-fed bridge inverse of Watkins-Johnson

Converters producing a unipolar output voltage

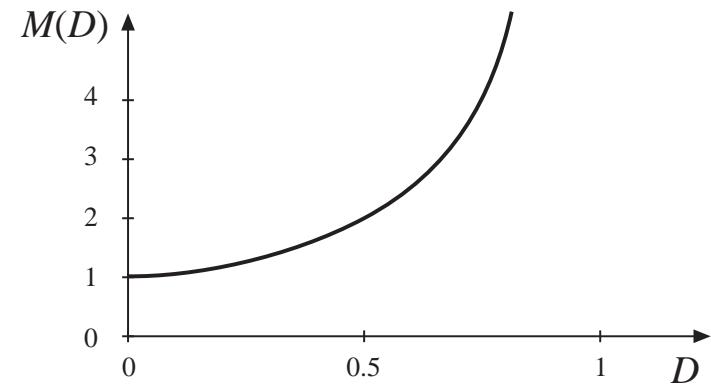
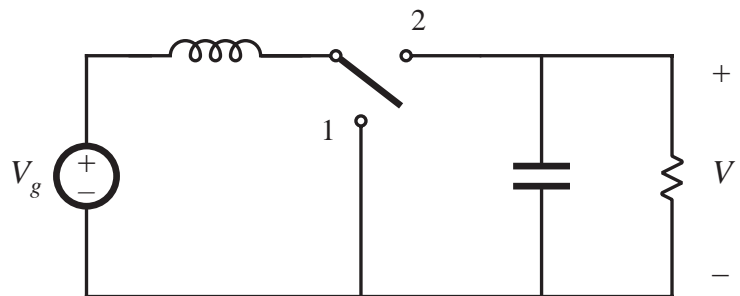
1. Buck

$$M(D) = D$$



2. Boost

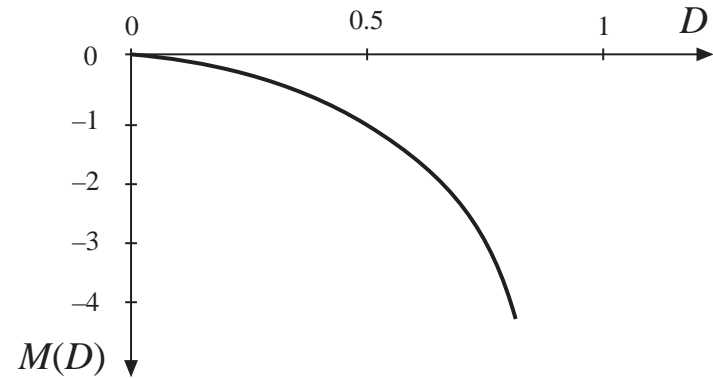
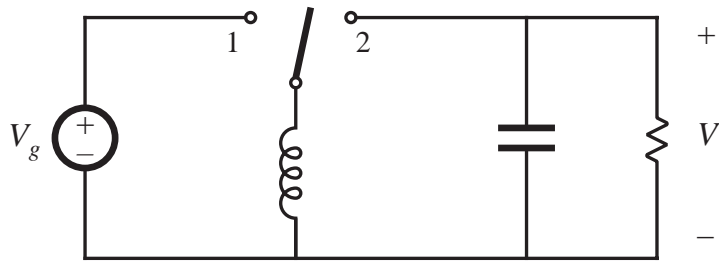
$$M(D) = \frac{1}{1-D}$$



Converters producing a unipolar output voltage

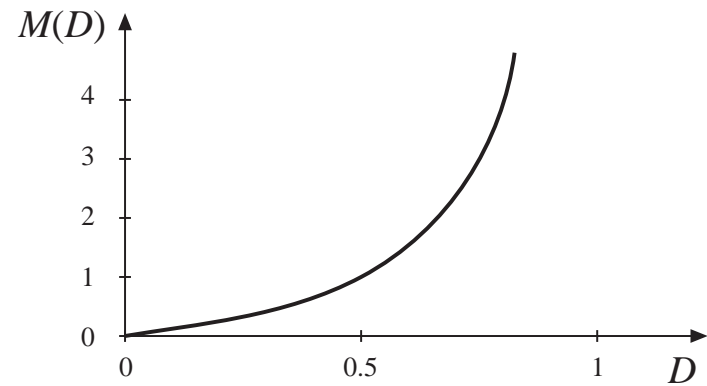
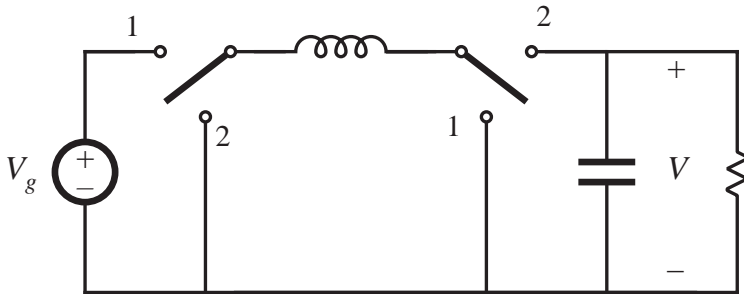
3. Buck-boost

$$M(D) = -\frac{D}{1-D}$$



4. Noninverting buck-boost

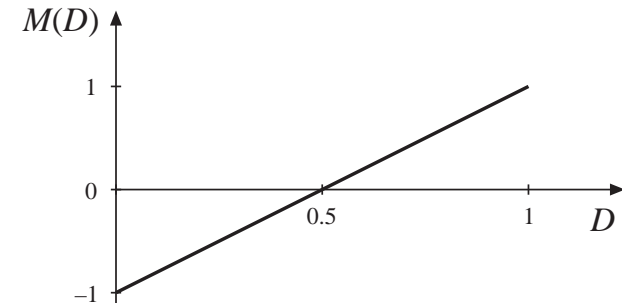
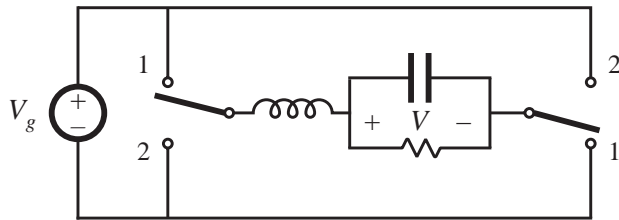
$$M(D) = \frac{D}{1-D}$$



Converters producing a bipolar output voltage suitable as dc-ac inverters

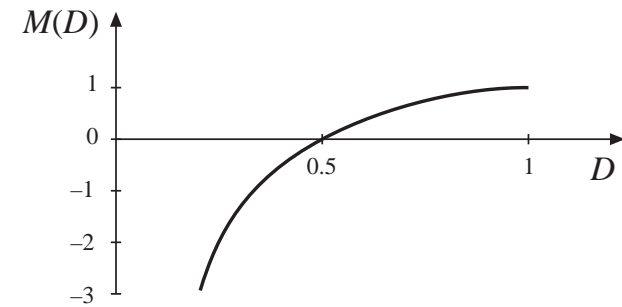
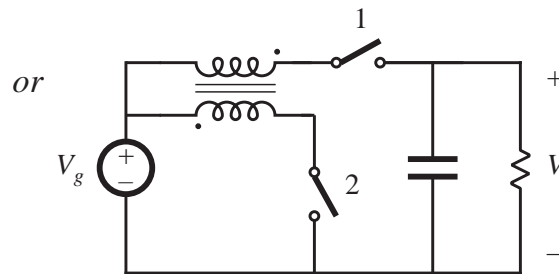
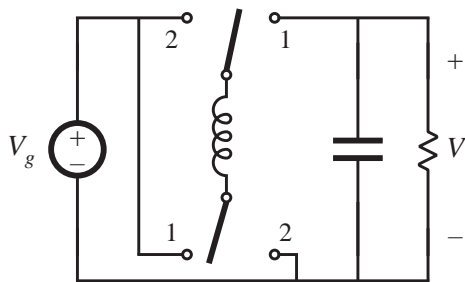
5. Bridge

$$M(D) = 2D - 1$$



6. Watkins-Johnson

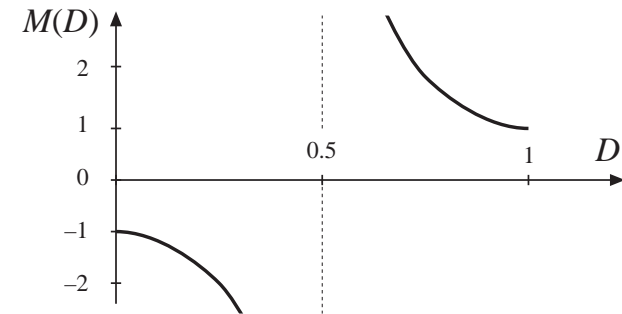
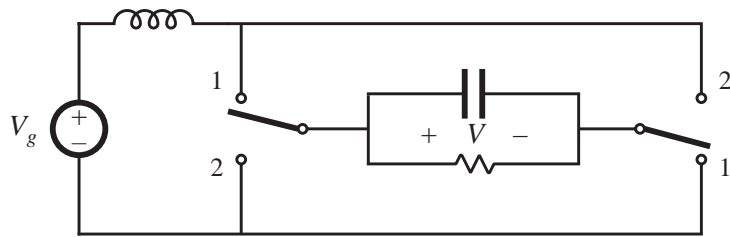
$$M(D) = \frac{2D - 1}{D}$$



Converters producing a bipolar output voltage suitable as ac-dc rectifiers

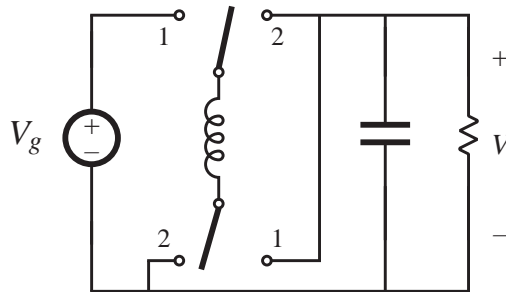
7. Current-fed bridge

$$M(D) = \frac{1}{2D - 1}$$

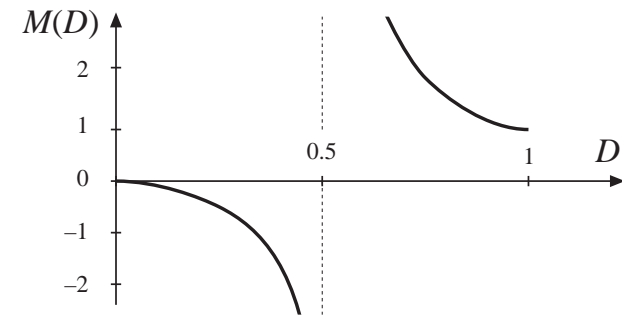
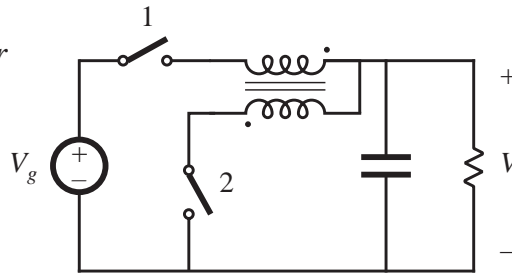


8. Inverse of Watkins-Johnson

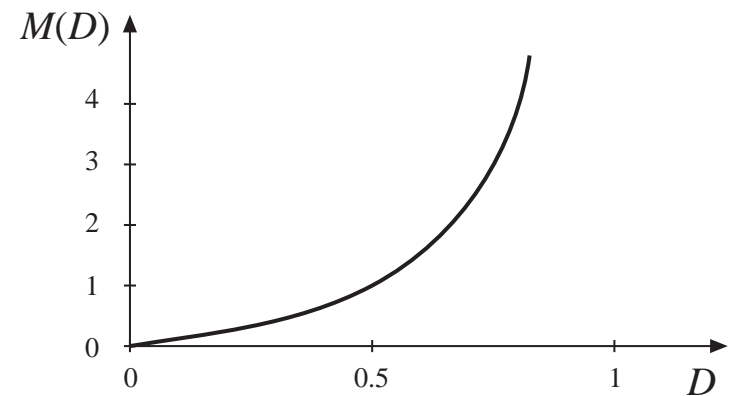
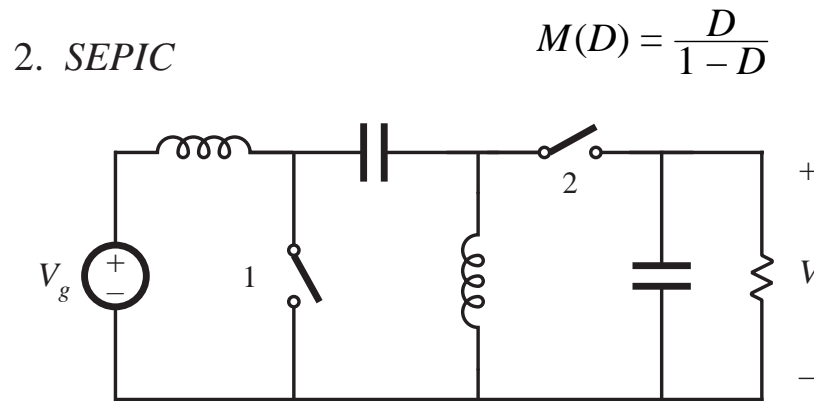
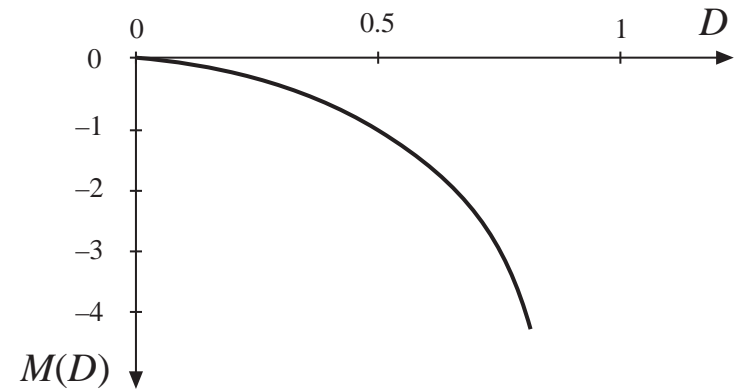
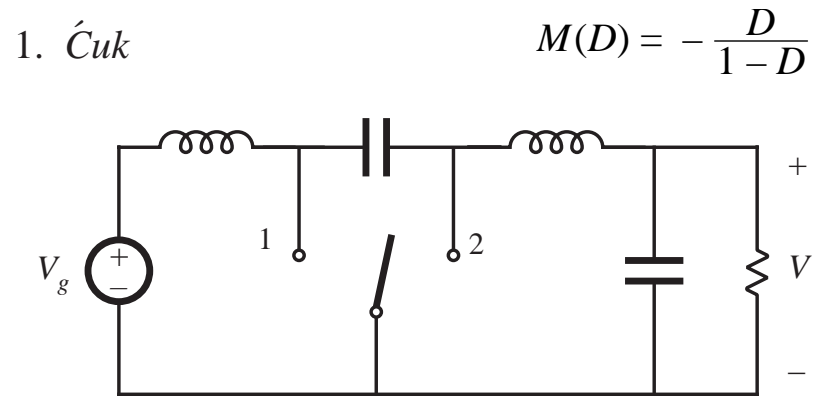
$$M(D) = \frac{D}{2D - 1}$$



or



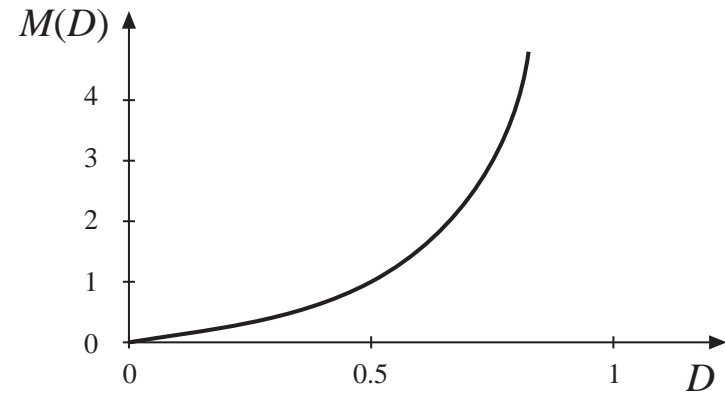
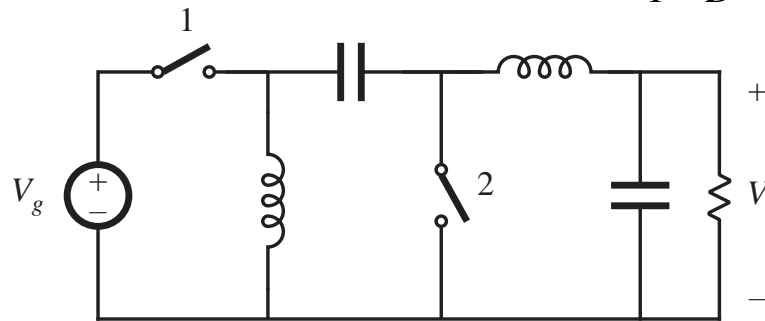
Several members of the class of two-inductor converters



Several members of the class of two-inductor converters

3. Inverse of SEPIC

$$M(D) = \frac{D}{1-D}$$



4. Buck²

$$M(D) = D^2$$

